Une modélisation de la mécanique des mousses

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F. Molino

C. Gay

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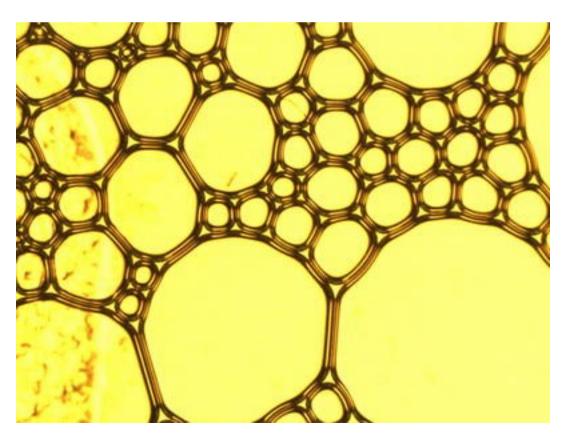
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Réponse mécanique d'un milieu mou

(wikipédia : rhéologie)

Faibles contraintes

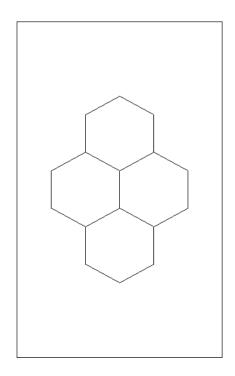
Élastique vs. visqueux

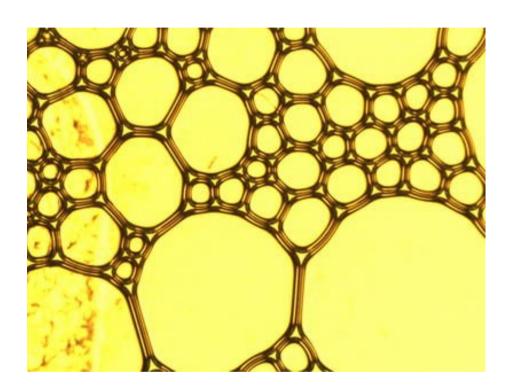
Liquide vs. solide

Fortes contraintes

Écoulement d'un solide : plasticité

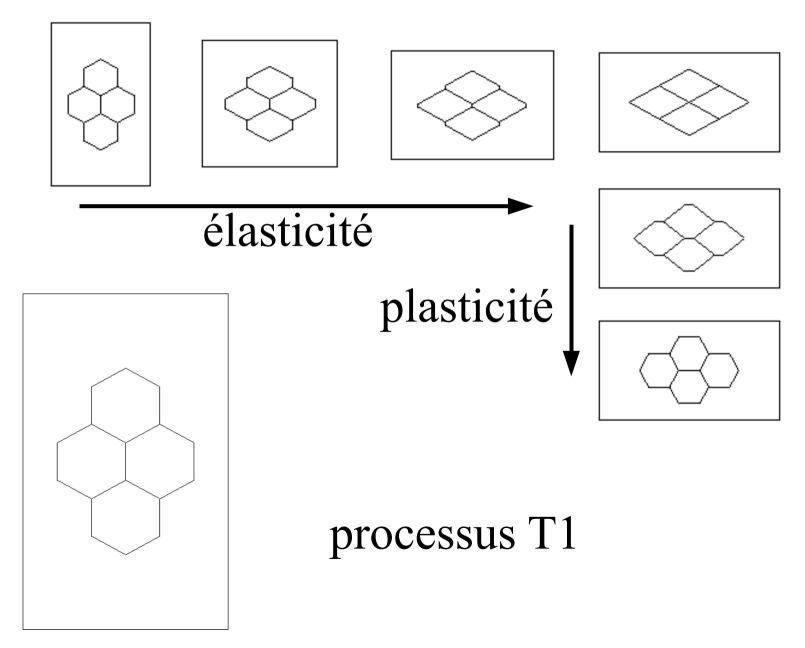
Une mousse





processus T1

Une mousse



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Plan

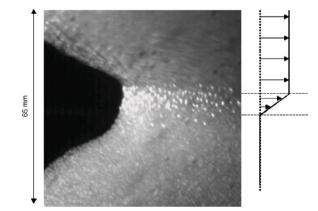
Mémoire du matériau et système de coordonnées

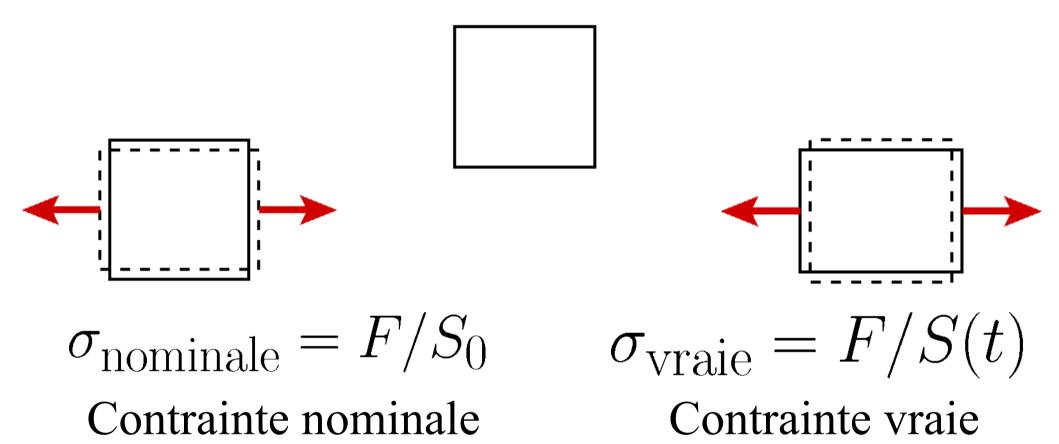
Élasticité:

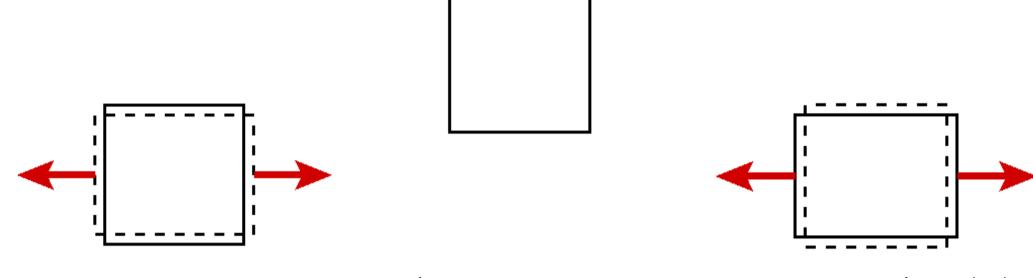
définitions de la déformation lois admissibles d'évolution de la contrainte

Plasticité, viscosité, modèle complet

Dilatance



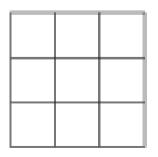


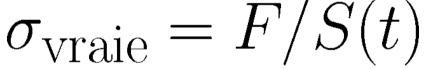


 $\sigma_{\text{nominale}} = F/S_0$

Contrainte nominale

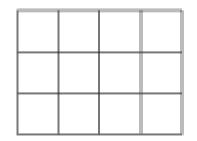
Approche lagrangienne



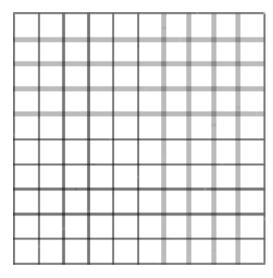


Contrainte vraie

Approche eulérienne

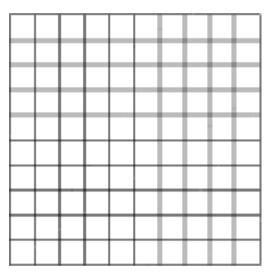


Élasticité



mémoire de l'état initial

Élasticité



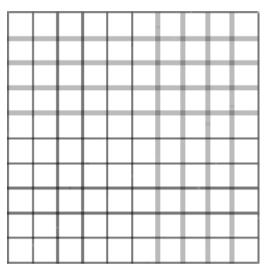
mémoire de l'état initial

Approche lagrangienne

Approche eulérienne

(Landau)

Élasticité



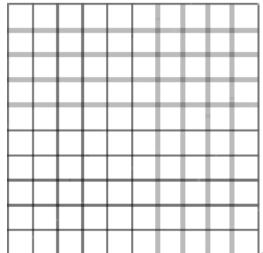
mémoire de l'état initial

Approche lagrangienne

Approche eulérienne

(Landau)

Mécanique des fluides



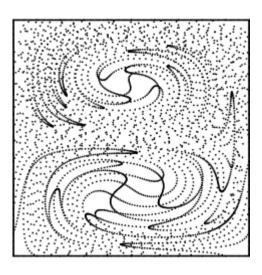
matériau sans mémoire

Approche eulérienne

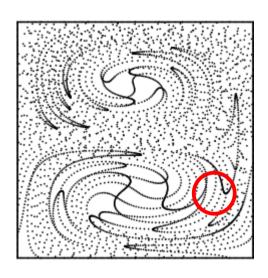
(Navier-Stokes)

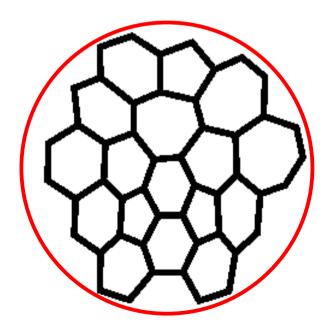
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Et les mousses?

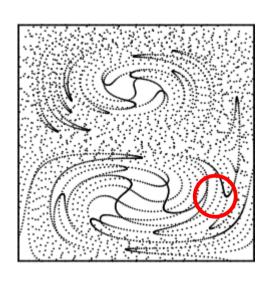


Et les mousses?



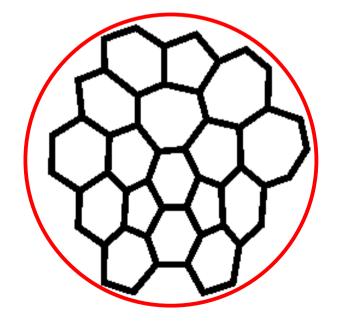


Et les mousses?



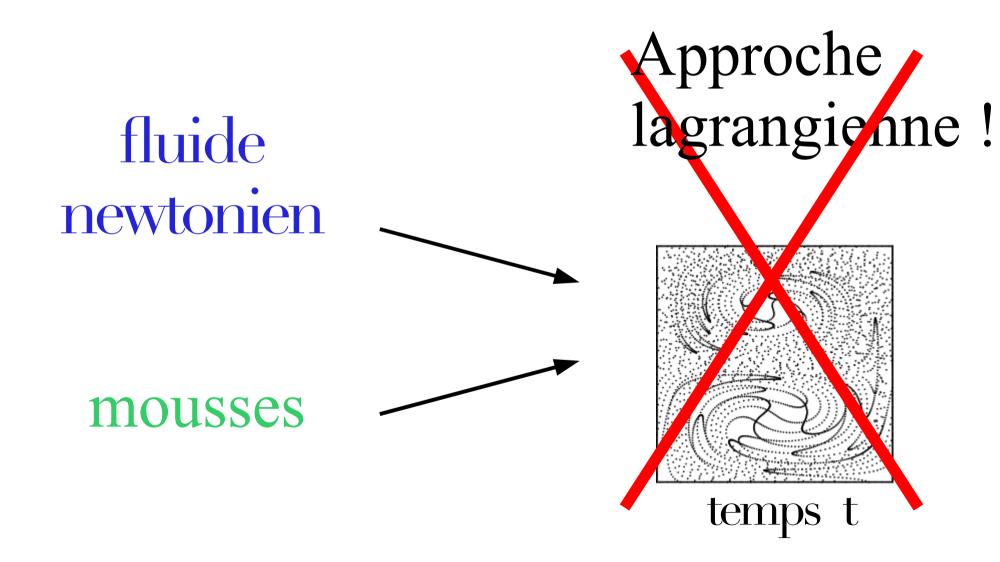
sans mémoire

T1



Approche eulérienne

Matériau sans mémoire :



Matériau sans mémoire :

Approche eulérienne! fluide newtonien mousses temps t

Plan

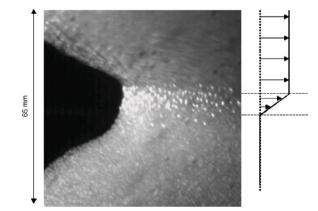
Mémoire du matériau et système de coordonnées

Élasticité:

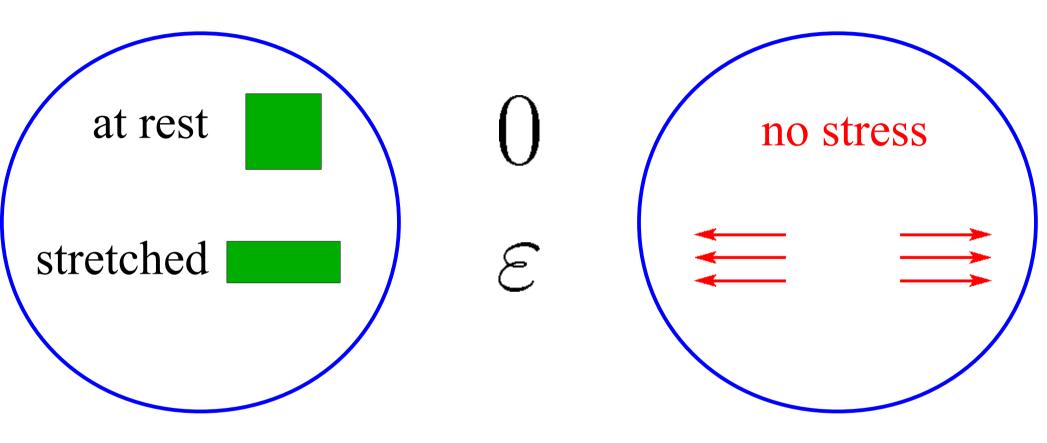
définitions de la déformation lois admissibles d'évolution de la contrainte

Plasticité, viscosité, modèle complet

Dilatance

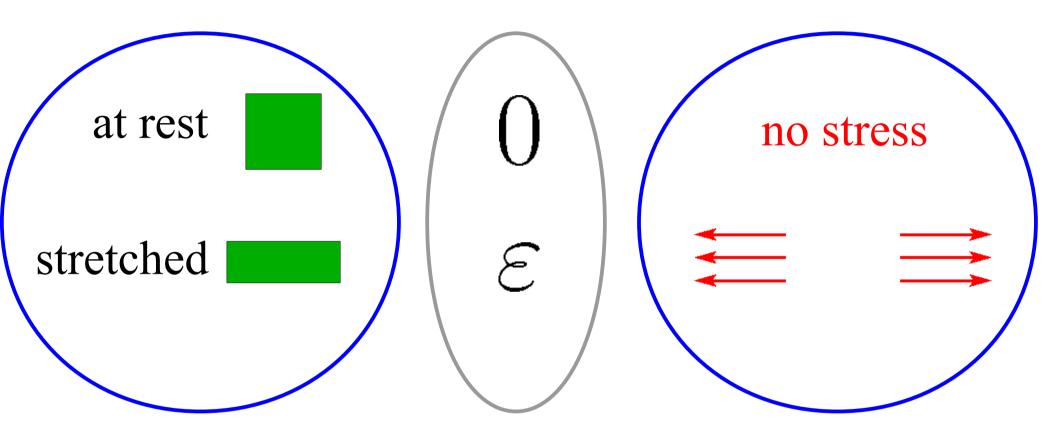


State - deformation - stress



physics (intrinsic)

State - deformation - stress



physics (intrinsic)

description (conventional: many deformations)

Many deformations

All deformations coincide at small deformations

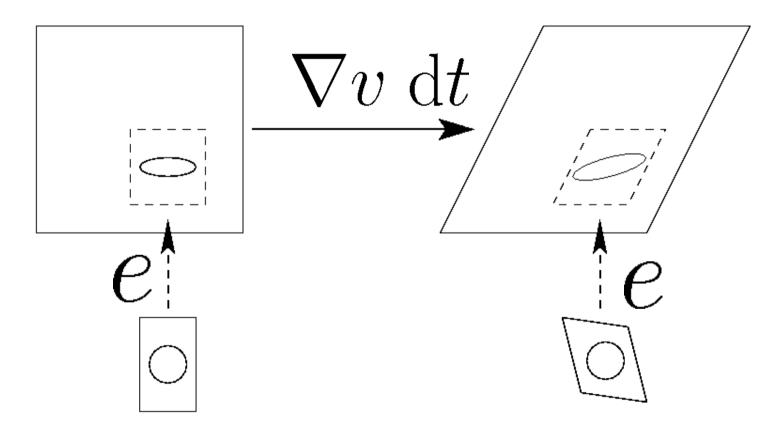
An elastic law is a relation : $e \leftrightarrow \sigma$

Many possible choices for the deformation: simple elastic law simple kinematics

• • •

Cinématique simple

$$\frac{\mathrm{D}e}{\mathrm{D}t} = f\left(\nabla v, e\right)$$



$$\frac{\mathrm{D}e}{\mathrm{D}t} = \frac{\partial e}{\partial t} + (v \cdot \nabla)e - \nabla v \cdot e - e \cdot \nabla v^{\mathrm{T}}$$

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kinematics
$$\nabla v$$
 \dot{e}
 \dot{e}
 $\dot{e} = \dot{e} (\nabla v, e)$

$$e \xrightarrow{\text{elastic law}} \sigma \quad \sigma = \sigma \, (e)$$
 kinematics ∇v

$$\dot{e} = \dot{e} \left(\nabla v, e \right)$$

kinematics
$$v$$

$$\dot{e} \xrightarrow{\text{elastic law}} \sigma$$

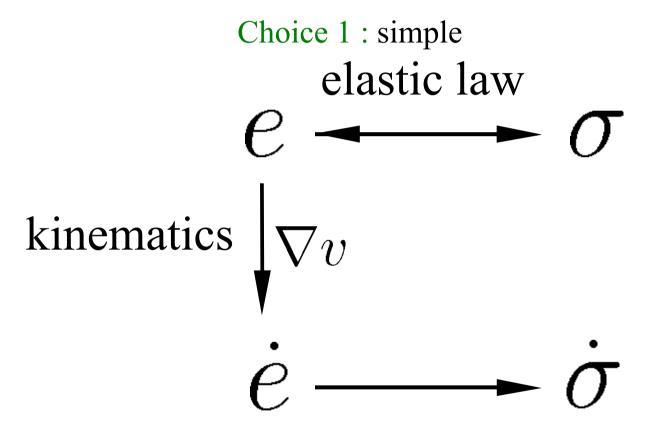
$$\dot{e} \xrightarrow{\dot{\sigma}} \dot{\sigma}$$

$$\dot{\sigma} = \dot{\sigma} (\nabla v, \sigma)$$

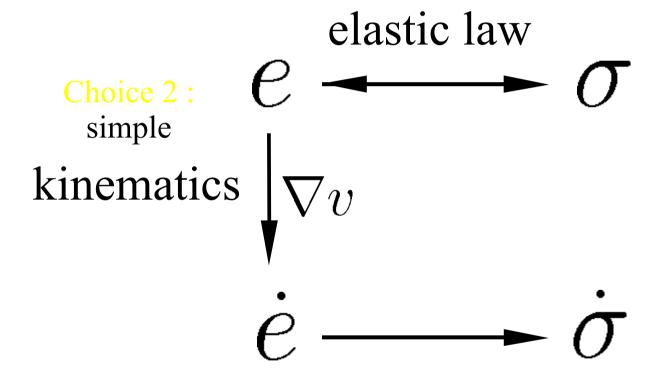
Bénito et al. Eur. Phys. J. E 2008

Which deformation elastic law should we choose? kinematics $|\nabla v|$ $\dot{\sigma} = \dot{\sigma} \left(\nabla v, \ \sigma \right)$

Choice



Choice



$$\begin{array}{c|c} \sigma \\ \nabla v & \text{my favourite rheological law} \\ \dot{\sigma} \\ \dot{\sigma} &= \dot{\sigma} \left(\nabla v, \sigma \right) \\ & \text{intrinsic!} \end{array}$$

for any choice of deformation e

$$\begin{array}{c|c} \sigma \\ \nabla v & \text{my favourite rheological law} \\ \dot{\sigma} \\ \dot{\sigma} &= \dot{\sigma} \left(\nabla v, \sigma \right) \\ & \text{intrinsic!} \end{array}$$

for any choice of deformation ρ $-\sigma \quad \sigma = \sigma(e)$ ∇v my favourite rheological law $\dot{\sigma} = \dot{\sigma} \left(\nabla v, \sigma \right)$
intrinsic!

for any choice of deformation ρ $\sigma = \sigma(e)$ ∇v my favourite rheological law $\dot{\sigma} = \dot{\sigma} (\nabla v, \sigma)$ intrinsic! $\dot{e} = \dot{e} \left(\nabla v, e \right)$

Évolution d'un tenseur

Vitesse
$$\nabla v = D + \Omega$$
 $\Omega = \frac{\nabla v - \nabla v^T}{2}$ $D = \frac{\nabla v + \nabla v + \nabla v^T}{2}$ $D = \frac{\nabla v + \nabla v +$

Comment évolue un tenseur symétrique ?

Évolution d'un tenseur

$$\dot{\sigma}=(\Omega\sigma-\sigma\Omega)+f(\sigma,\ D,\ \dot{D},...)$$
 dérivée particulaire

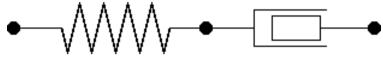
dérivée convective

autre...

équations constitutives...

Équations constitutives

Maxwell



$$\dot{\sigma} = (\Omega \sigma - \sigma \Omega) + (D\sigma + \sigma D) + 2\mu D - \sigma/\tau$$

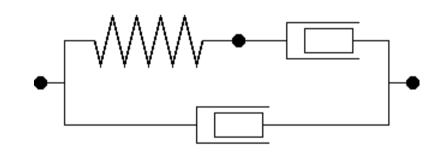
$$\dot{\sigma} = (\Omega \sigma - \sigma \Omega) - (D\sigma + \sigma D) + 2\mu D - \sigma/\tau$$

$$\dot{\sigma} = (\Omega \sigma - \sigma \Omega) + 2\mu D - \sigma/\tau$$

$$+ 2\mu D - \sigma/\tau$$

Jeffrey / Oldroyd

$$\sigma_{\rm tot} = \sigma + 2\eta D$$



Élasticité:
$$\dot{\sigma} = (\Omega \sigma - \sigma \Omega) + f(\sigma) : D$$

Kinematic validity of some classical rheological laws

upper-convected used for some materials

$$\dot{\sigma} = 2\mu D + \nabla v \cdot \sigma + \sigma \cdot (\nabla v)^{T}$$

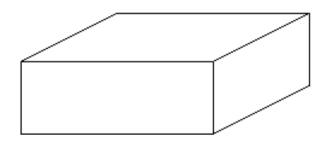
lower-convected used for some other materials

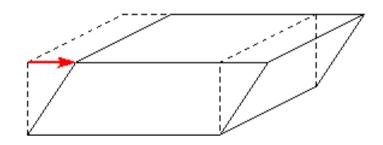
$$\dot{\sigma} = 2\mu \ D - (\nabla v)^T \cdot \sigma - \sigma \cdot \nabla v$$

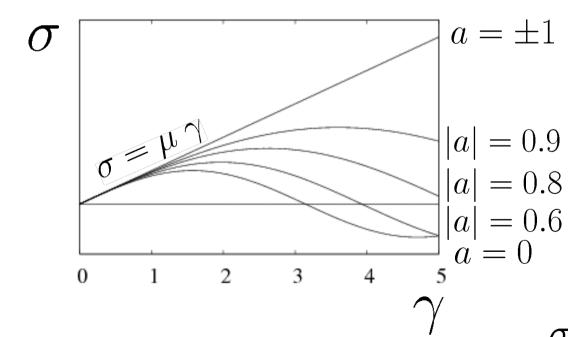
corotational used for yet other materials

$$\dot{\sigma} = 2\mu D + \dot{\omega} \cdot \sigma - \sigma \cdot \dot{\omega}$$

Loi élastique?



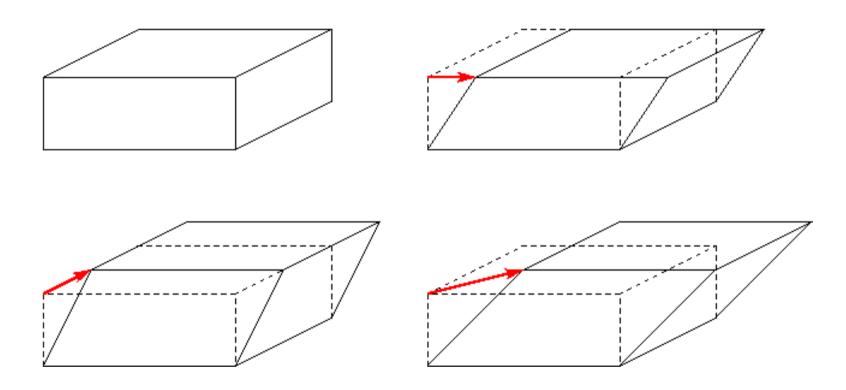




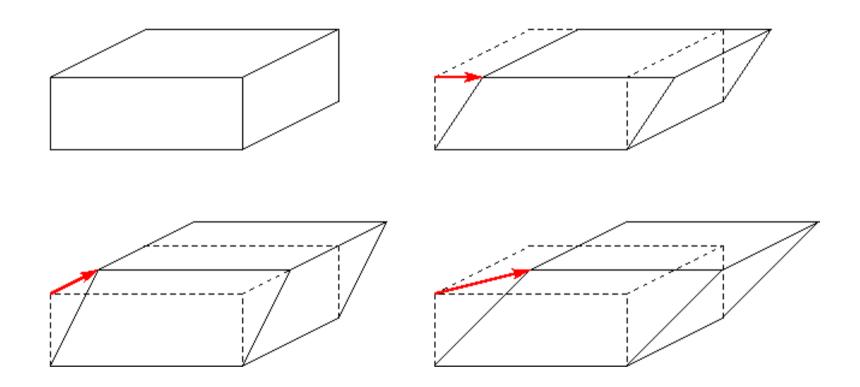
cisaillement permanent : contrainte oscillante!?

$$\sigma = \frac{\mu}{\sqrt{1 - a^2}} \sin\left(\gamma \sqrt{1 - a^2}\right)$$

Loi élastique?



Loi élastique?



la contrainte finale dépend du chemin emprunté!?

Kinematic validity of some classical rheological laws

small elastic deformations

large elastic deformations

upper-convected (a=+1) Valid

lower-convected (a=-1) valid

corotational (a=0)

other interpolated (-1<a<+1) Valid Gordon, Schowalter, 1972

other derivatives

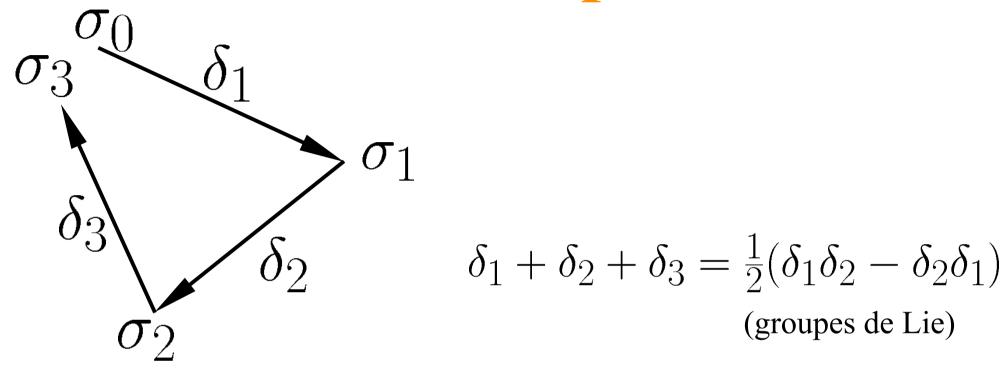
valid valid

valid

valid valid not valid not valid

?

Chemin emprunté



$$\dot{\sigma} = (\Omega \sigma - \sigma \Omega) + f(\sigma) : D$$

Condition:

$$(f'(\sigma):(f(\sigma):D_2)):D_1-(f'(\sigma):(f(\sigma):D_1)):D_2$$

= $D_1D_2\sigma + \sigma D_2D_1 - \text{v.v.}$

Évolutions imaginables

$$\dot{\sigma} = (\Omega \sigma - \sigma \Omega) + f(\sigma) : D$$

$$\operatorname{tr}(D) I$$

$$\operatorname{tr}(D) \sigma$$

$$\operatorname{tr}(\sigma D) I \qquad D$$

$$\operatorname{tr}(\sigma D) \sigma \qquad \sigma D + D\sigma$$

$$\operatorname{tr}(\sigma D) \sigma^{2} \qquad \sigma^{2}D + D\sigma^{2}$$

$$\operatorname{tr}(\sigma^{2}D) I \qquad \sigma D\sigma$$

$$\operatorname{tr}(\sigma^{2}D) \sigma \qquad \sigma^{2}D\sigma + \sigma D\sigma^{2}$$

$$\operatorname{tr}(\sigma^{2}D) \sigma^{2} \qquad \sigma^{2}D\sigma^{2}$$

Évolutions imaginables

$$\dot{\sigma} = (\Omega \sigma - \sigma \Omega) + f(\sigma) : D$$

$$\operatorname{tr}(D) I \bigstar$$

$$\operatorname{tr}(D) \sigma \bigstar$$

$$\operatorname{tr}(\sigma D) I \qquad \operatorname{tr}(D) \sigma^{2} \bigstar D$$

$$\operatorname{tr}(\sigma D) \sigma \bigstar \qquad \sigma D + D\sigma$$

$$\operatorname{tr}(\sigma D) \sigma^{2} \qquad \sigma^{2}D + D\sigma^{2}$$

$$\operatorname{tr}(\sigma^{2}D) I \qquad \sigma D\sigma$$

$$\operatorname{tr}(\sigma^{2}D) \sigma \bigstar \qquad \sigma^{2}D\sigma + \sigma D\sigma^{2}$$

$$\operatorname{tr}(\sigma^{2}D) \sigma^{2} \qquad \sigma^{2}D\sigma^{2}$$

Évolutions imaginables

$$\dot{\sigma} = (\Omega \sigma - \sigma \Omega) + f(\sigma) : D$$

$$\operatorname{tr}(D) I \bigstar$$

$$\operatorname{tr}(D) \sigma \bigstar$$

$$\operatorname{tr}(\sigma D) I \qquad \operatorname{tr}(D) \sigma^{2} \bigstar \qquad D \bigstar$$

$$\operatorname{tr}(\sigma D) \sigma \bigstar \qquad \sigma D + D\sigma \bigstar$$

$$\operatorname{tr}(\sigma D) \sigma^{2} \qquad \sigma^{2}D + D\sigma^{2}$$

$$\operatorname{tr}(\sigma^{2}D) I \qquad \sigma D\sigma$$

$$\operatorname{tr}(\sigma^{2}D) \sigma \bigstar \qquad \sigma^{2}D\sigma + \sigma D\sigma^{2}$$

$$\operatorname{tr}(\sigma^{2}D) \sigma^{2} \qquad \sigma^{2}D\sigma^{2}$$

Évolutions admissibles

$$\dot{\sigma} = (\Omega \sigma - \sigma \Omega) \pm (\sigma D + D \sigma) \\ + 2 \mu D \star \\ + \text{tr}(D) (\dot{s_1}(\sigma)I + \dot{s_2}(\sigma)\sigma + \dot{s_3}(\sigma) \sigma^2) \\ + \dot{s_5}(\sigma) \text{tr}(\sigma D) \sigma \\ + \dot{s_8}(\sigma) \text{tr}(\sigma^2 D) \sigma \\ + \cdots ? \qquad \text{signification mécanique ?}$$

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Évolutions admissibles

rotation

$$\dot{\sigma} = (\Omega \sigma - \sigma \Omega) \pm (\sigma D + D\sigma)$$

$$+2~\mu~D$$
 élasticité linéaire

compressibilité

$$+\operatorname{tr}(D) \left(s_1(\sigma)I + s_2(\sigma)\sigma + s_3(\sigma)\sigma^2\right)$$

$$+s_5(\sigma) \operatorname{tr}(\sigma D) \sigma$$

 $+s_8(\sigma) \operatorname{tr}(\sigma^2 D) \sigma$

effets non linéaires

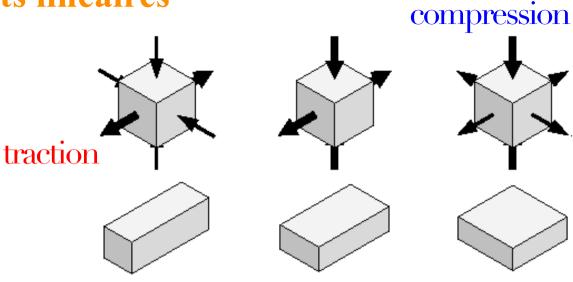
$$+s_8(\sigma) \operatorname{tr}(\sigma^2 D) \sigma$$

Valable pour les mousses

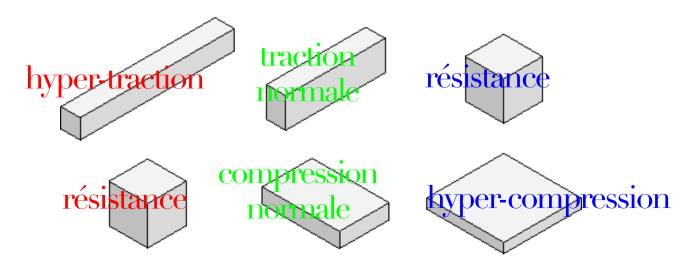
et pour tout système très déformable

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Effets linéaires



Effets non linéaires



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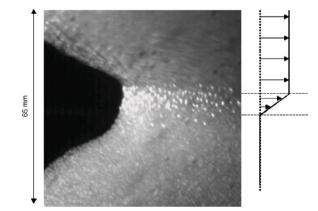
Plan

Mémoire du matériau et système de coordonnées

Élasticité:

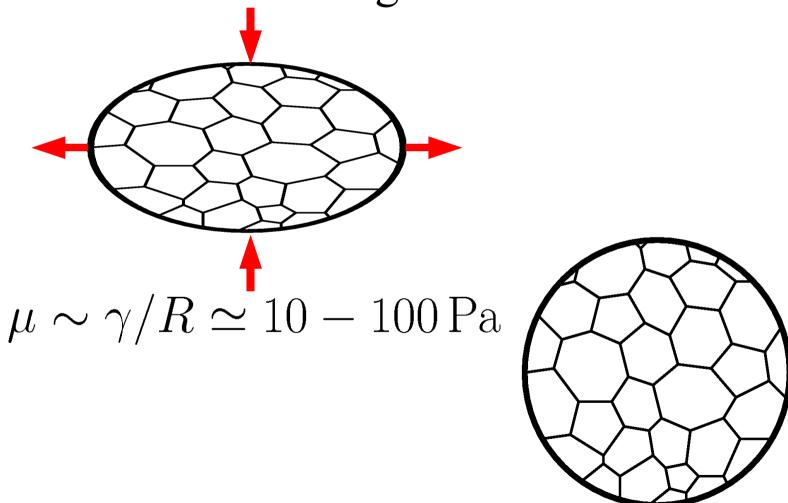
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Plasticité, viscosité, modèle complet

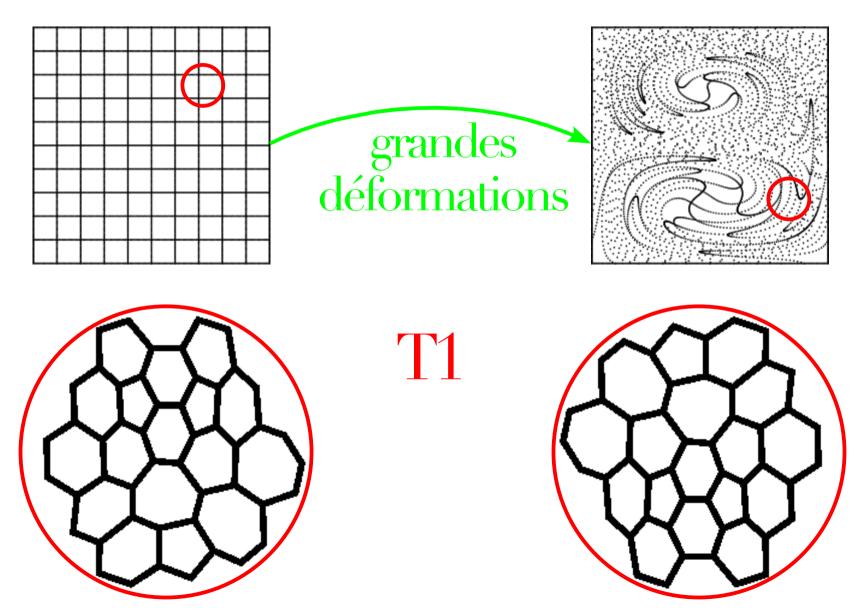


Modules élastiques $R \simeq 1 \, \mathrm{mm}$

Cisaillement / élongation

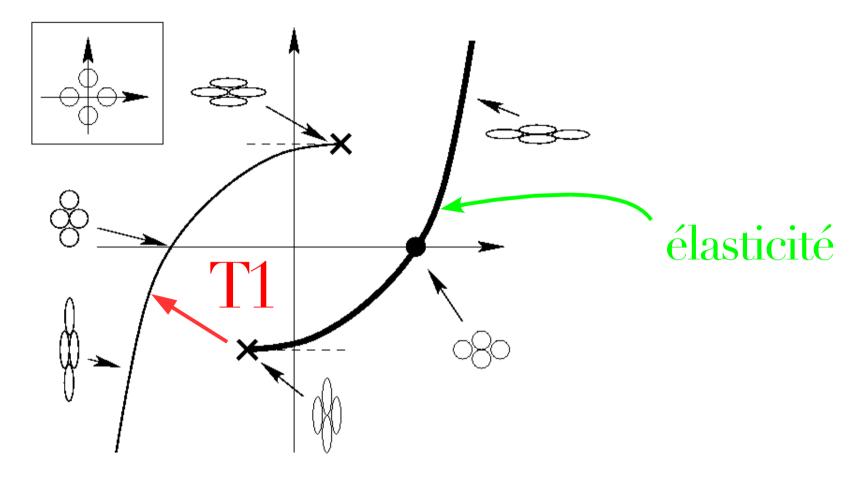


Origine de la plasticité d'une mousse

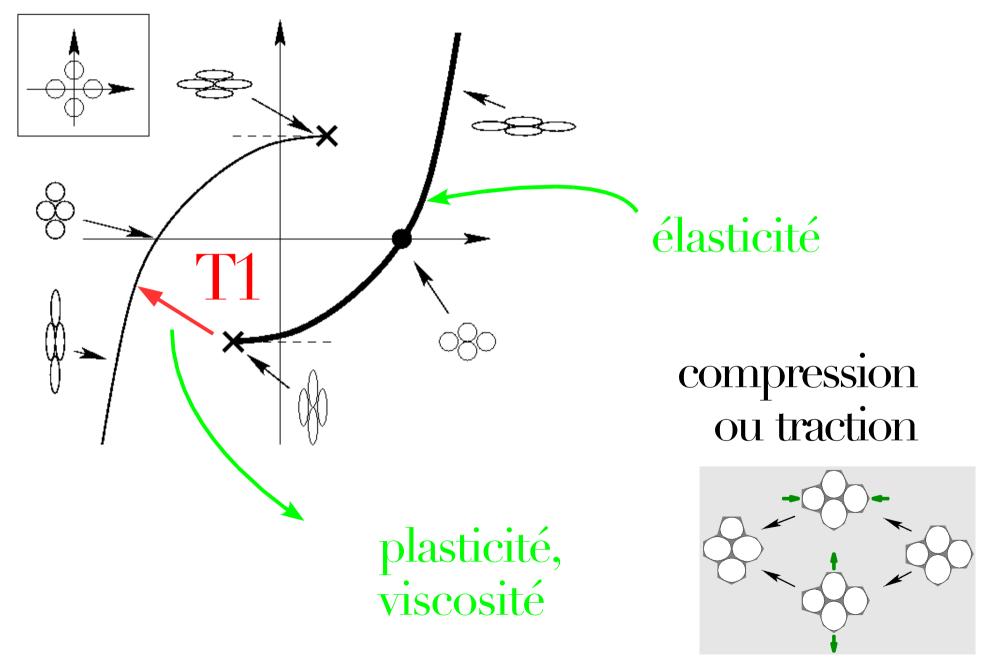


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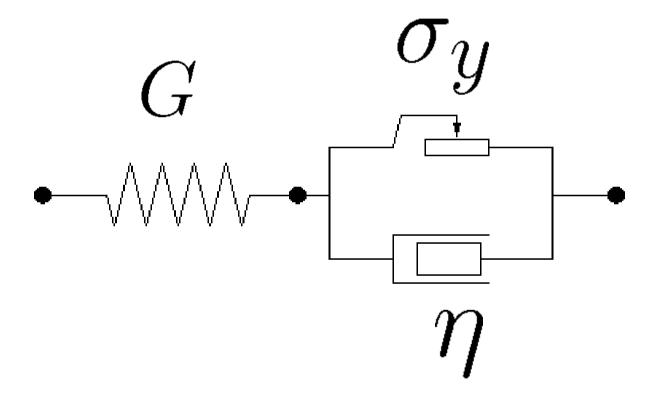
Origine de la plasticité d'une mousse



Origine de la plasticité d'une mousse

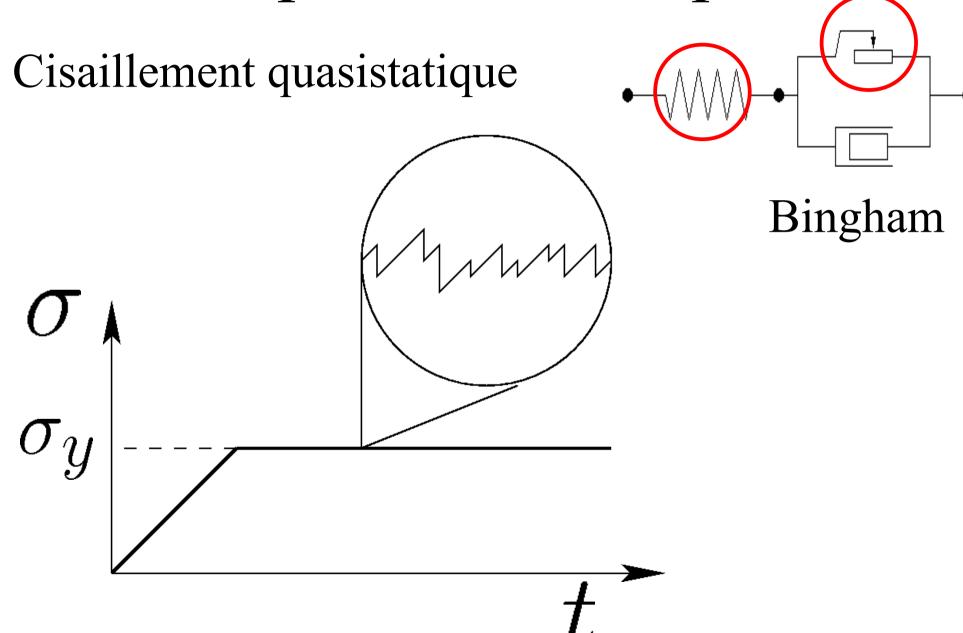


Comportement simplifié



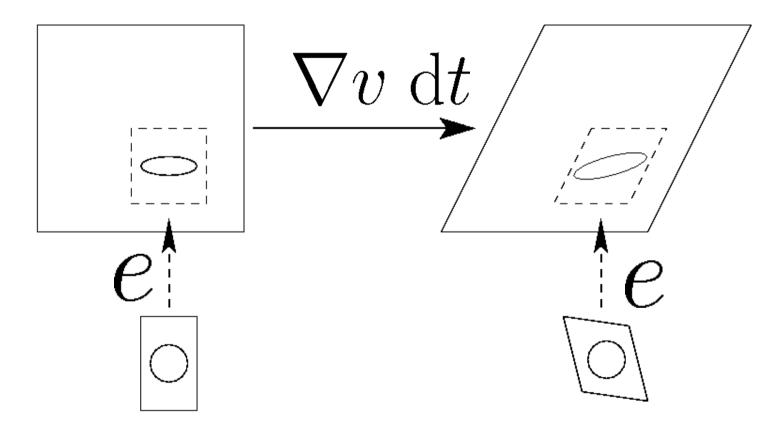
Bingham

Comportement simplifié



Formulation tensorielle

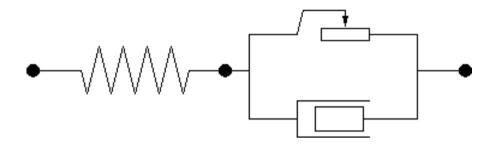
$$\frac{\mathrm{D}e}{\mathrm{D}t} = f\left(\nabla v, e\right)$$



$$\frac{\mathrm{D}e}{\mathrm{D}t} = \frac{\partial e}{\partial t} + (v \cdot \nabla)e - \nabla v \cdot e - e \cdot \nabla v^{\mathrm{T}}$$

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Formulation tensorielle



Déformations élastique et plastique

$$D = \frac{De}{Dt} + D_{pl}$$

$$D_{\rm pl} = D_{\rm pl}(s) = D_{\rm pl}(e)$$

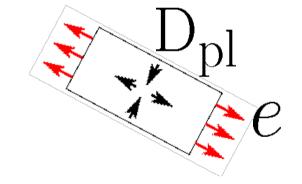
Déformation plastique

Forme tensorielle générale

$$D_{pl} = A_0 I + A_1 e + A_2 e^2$$

Incompressibilité

Deux fonctions indépendantes



Dissipation positive

Second principe

Système complet d'équations

$$e \leftrightarrow s$$

$$\frac{\partial e}{\partial t} + (v \cdot \nabla)e = D + \nabla v \cdot e + e \cdot \nabla v^{\mathrm{T}}$$
$$-A_0(e) I - A_1(e) e - A_2(e) e^2$$

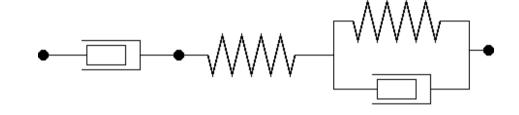
$$divs = gradp$$

$$\mathrm{div} v = 0$$
 Bénito et al. Eur. Phys. J. E 2008

Autres modèles : modèles scalaires

Höhler, Cohen-Addad (2004)

fluage à faible contrainte (mûrissement,...)



Janiaud, Weaire, Hutzler (2006)

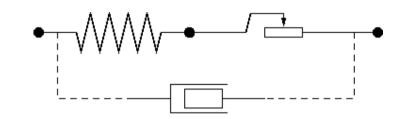
mousse 2D entre deux plaques, vitesse radiale $v_{\it A}(r)$



Autres modèles : modèles tensoriels

Marmottant, Graner (2007)

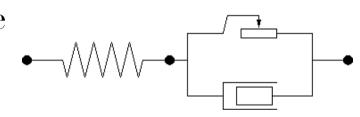
linéaire



Takeshi, Sekimoto (2005) $v_z(x, y)$ linéaire

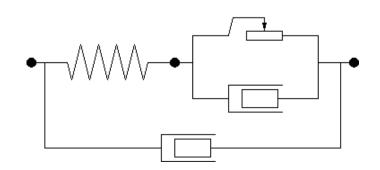
Bénito et al. (2008)

non-linéaire (générique)

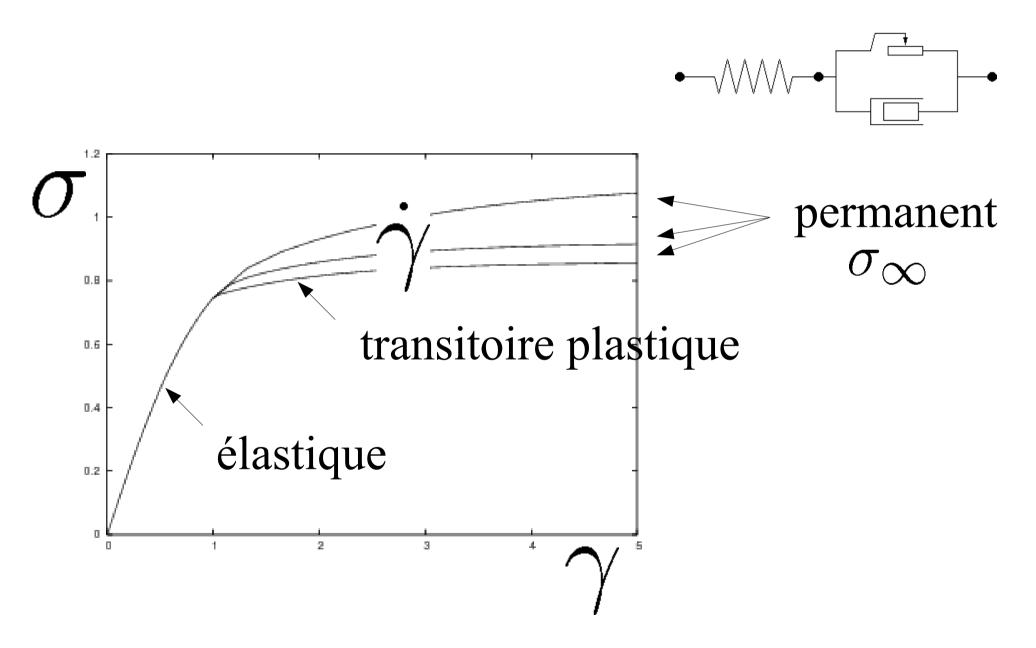


Saramito (2007)

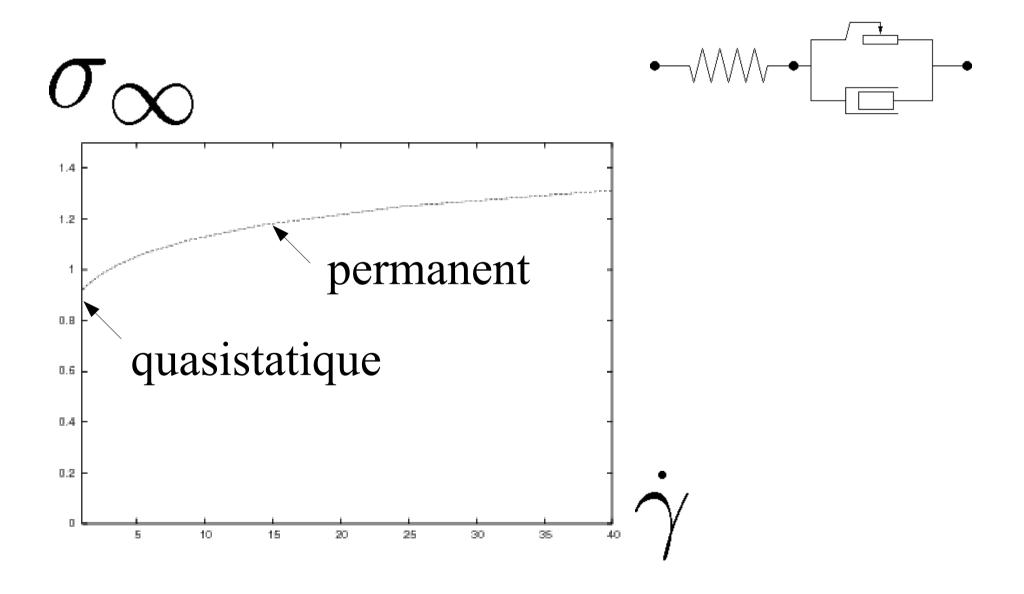
linéaire



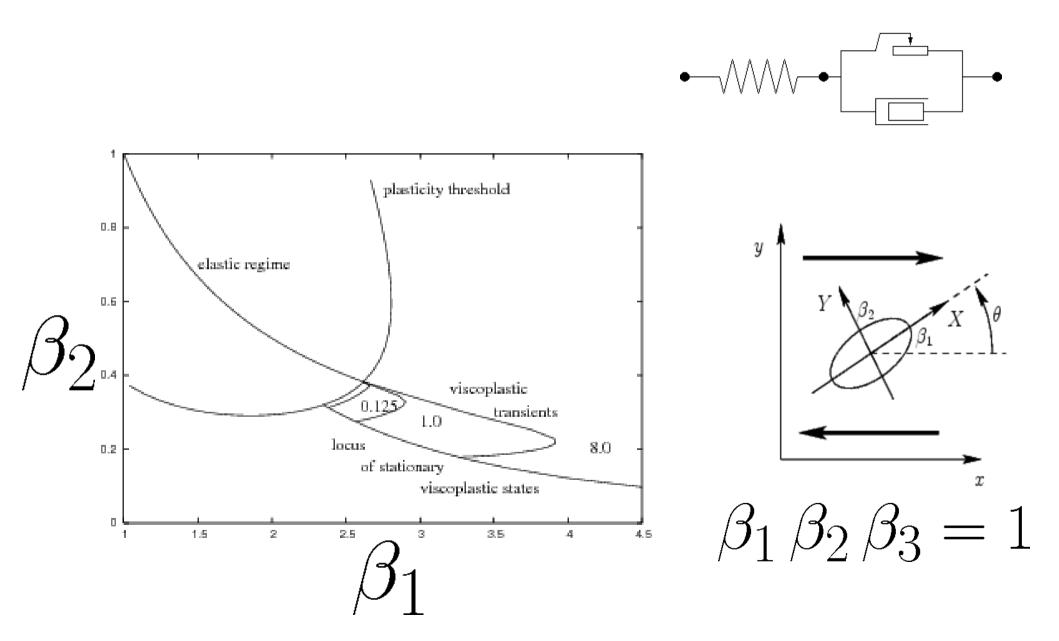
Cisaillement homogène constant



Cisaillement homogène constant



Cisaillement homogène constant



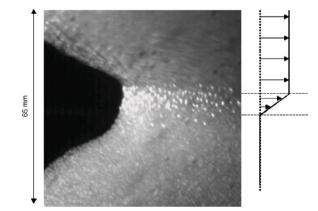
Plan

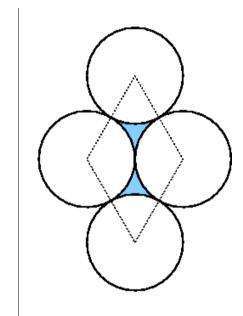
Mémoire du matériau et système de coordonnées

Élasticité:

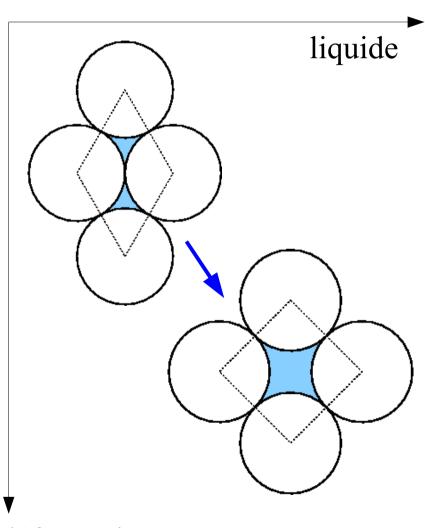
définitions de la déformation lois admissibles d'évolution de la contrainte

Plasticité, viscosité, modèle complet

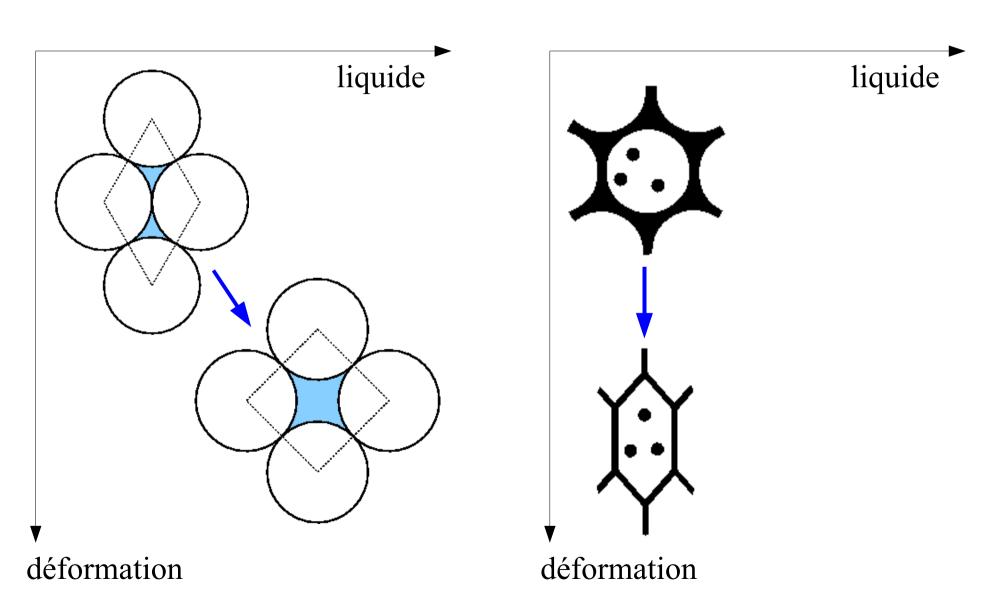


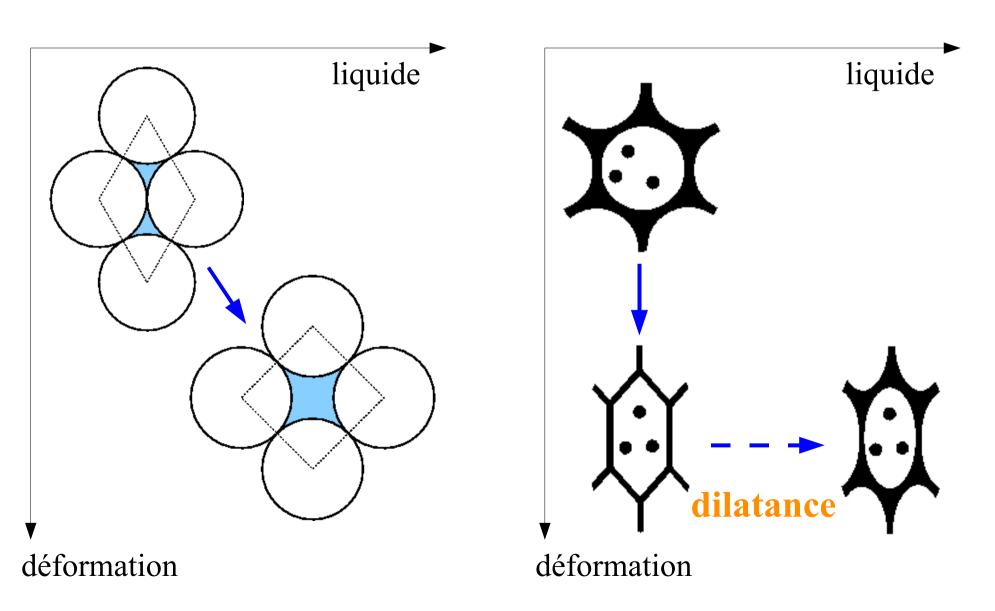


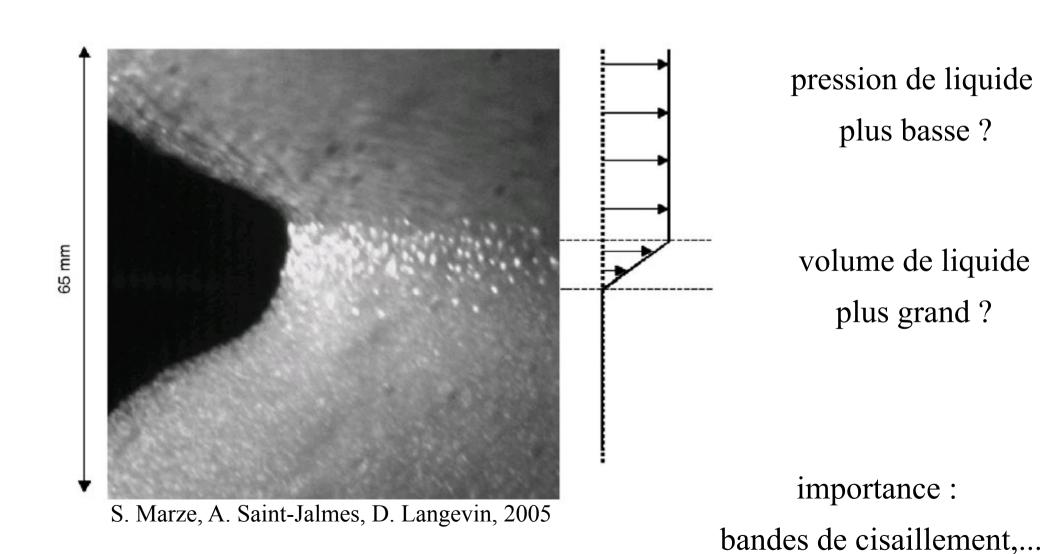




déformation







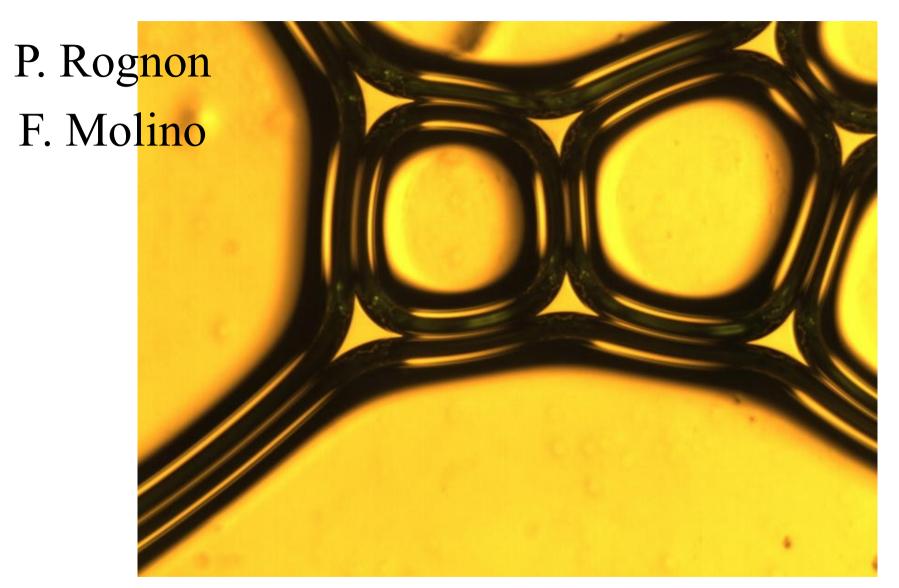
Dilatance statique

D. Weaire, S. Hutzler, F. Rioual, 2003, 2005

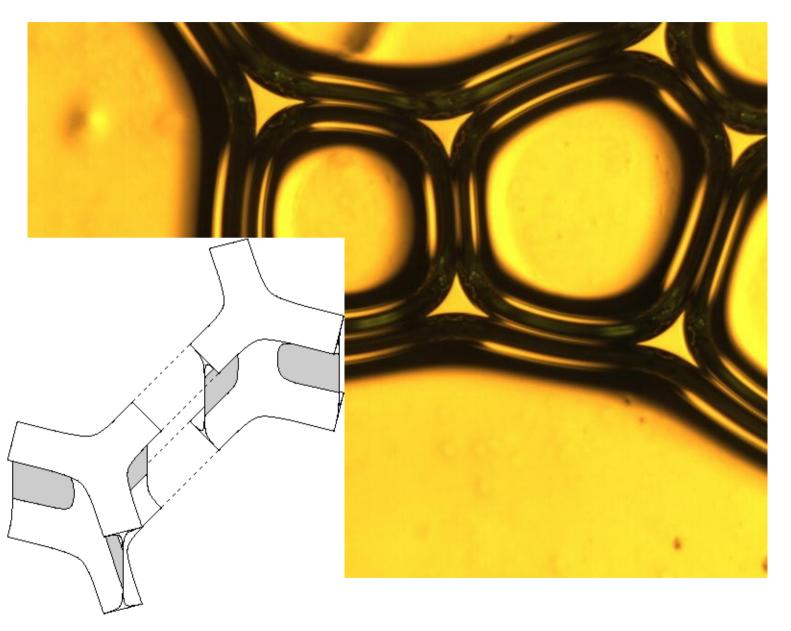
Dilatance dans une mousse 2D

(explication thermodynamique)

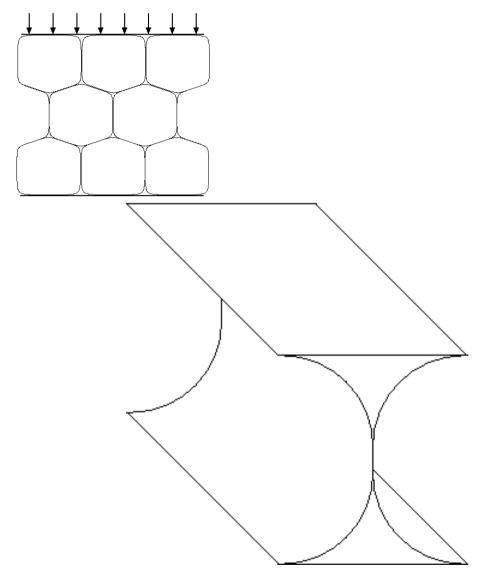
Dilatance = géométrie?



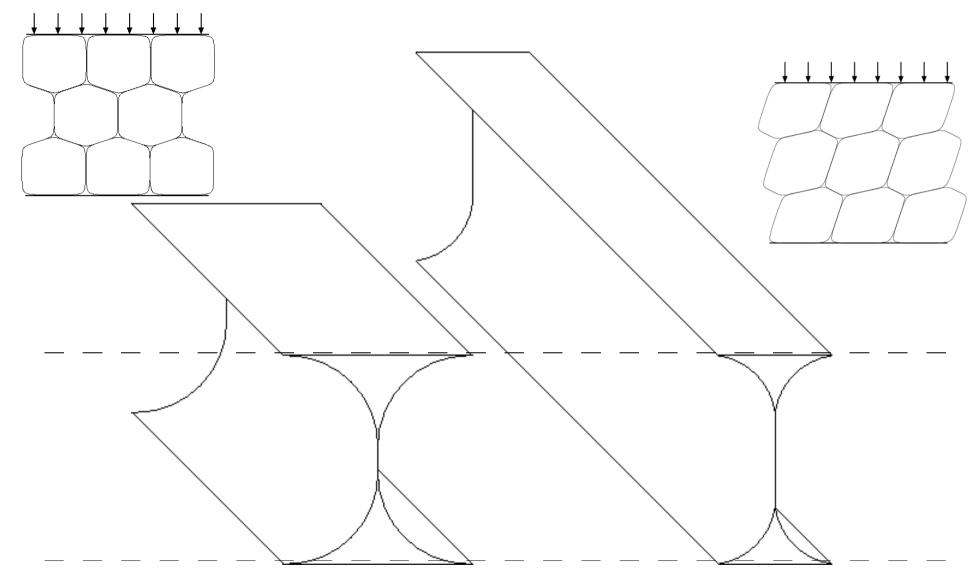
Dilatance = géométrie?



Dilatance = géométrie ?



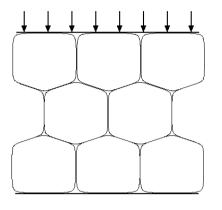
Dilatance = géométrie?

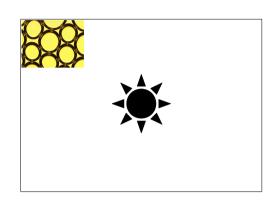


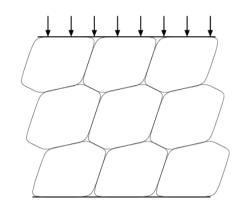
volume = périmètre x section

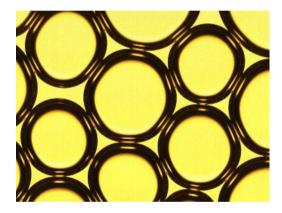
Test expériental

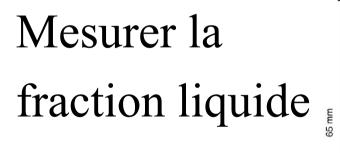
C. Derec, F. Élias, M.-A. Guedeau-Boudeville, D. Osmani

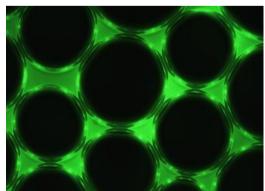


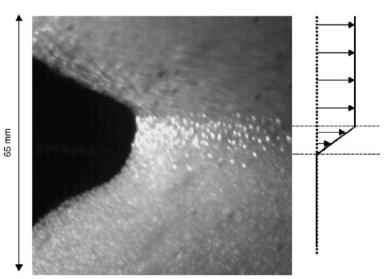








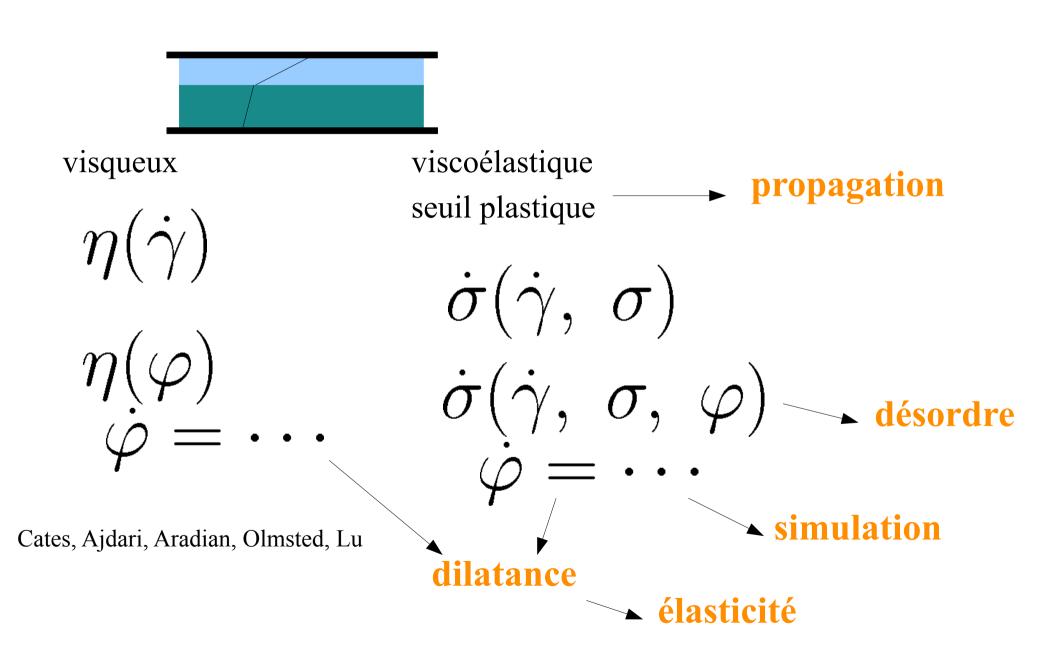


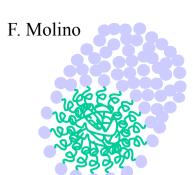


Effet attendu: 1,15

S. Marze, A. Saint-Jalmes, D. Langevin, 2005

Bandes de cisaillement



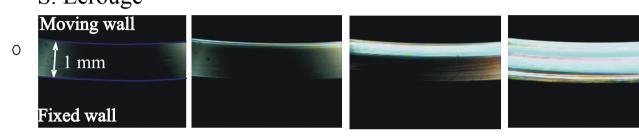


Micelles géantes

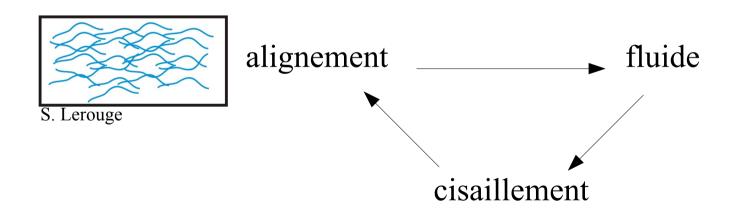
S. Lerouge



S. Lerouge

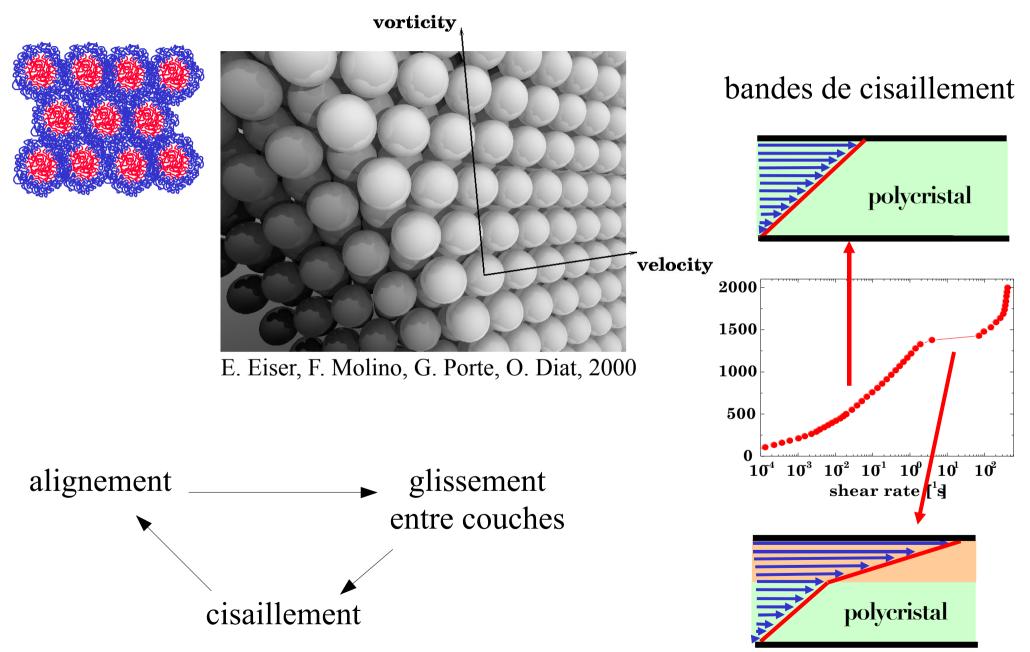


bandes de cisaillement



S. Lerouge

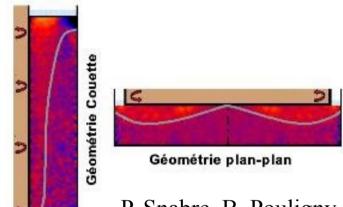
Phases cubiques de copolymères



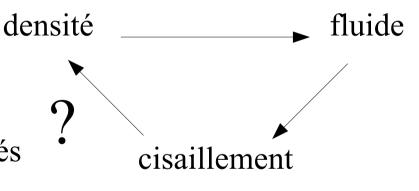
Granulaire

solide plastique

bandes de cisaillement

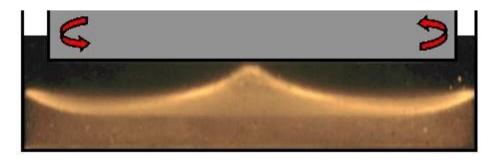


P. Snabre, B. Pouligny



contacts lubrifiés dilatance

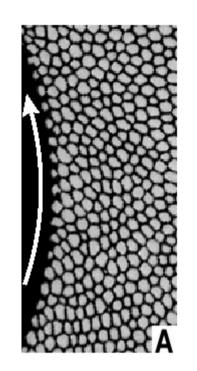
M. Lenoble, B. Pouligny

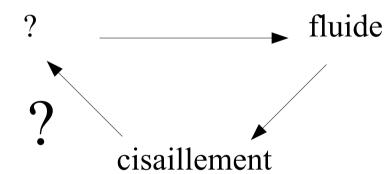


Mousse

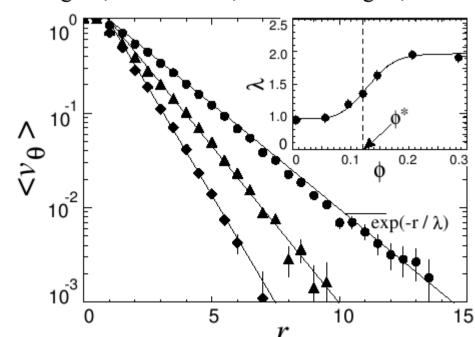
solide visco-élasto-plastique

bandes de cisaillement





propagation désordre dilatance G. Debrégeas, H. Tabuteau, J.-M. Di Meglio, 2001



Conclusion

$$\frac{\partial e}{\partial t} + (v \cdot \nabla)e = D + \nabla v \cdot e + e \cdot \nabla v^{\mathrm{T}}$$
$$-A_0(e) \mathrm{I} - A_1(e) e - A_2(e) e^2$$

S. Bénito, C.-H. Bruneau, T. Colin, F. Molino

